



IFTOMM sponsored conference Mechanism Design for Robotics

MEDER

A Poster on the activities

by prof. Marco Ceccarelli, Roma Tor Vergata University, Italy
Updated: March 2021

Mechanism Design for Robots can be considered fundamental to ensure proper performance by a robot in assigned tasks.

MEDER is aimed to collect designs and developments of the mechanical design and operation of robots by looking at the advances in solutions and procedures that can provide enhancements in robot structures and their functionalities even in new areas of application.

Papers are solicited mainly in the topics that are related to robot design and functioning from theory up to practical applications.

International Scientific Committee

- Marco Ceccarelli (Univ. of Cassino, Italy, Chair)
- Ding Xilun (Beihang Univ., China)
- Grigore Gogu (SIGMA Clermont, France)
- Mario Acevedo (Univ. Panamericana, Mexico)
- Shaoping Bai (Aalborg Univ., Denmark)
- Yukio Takeda (Tokyo Inst Tech., Japan)
- Alba Perez (Idaho State Univ., USA)
- Yan Jin (Belfast Univ., UK)
- Erwin Lovasz (Politehnica Univ. Timisoara, Romania)
- Said Zeghloul (Poitiers Univ., France)
- Victor Petuya (Univ. of Basque Country, Spain)

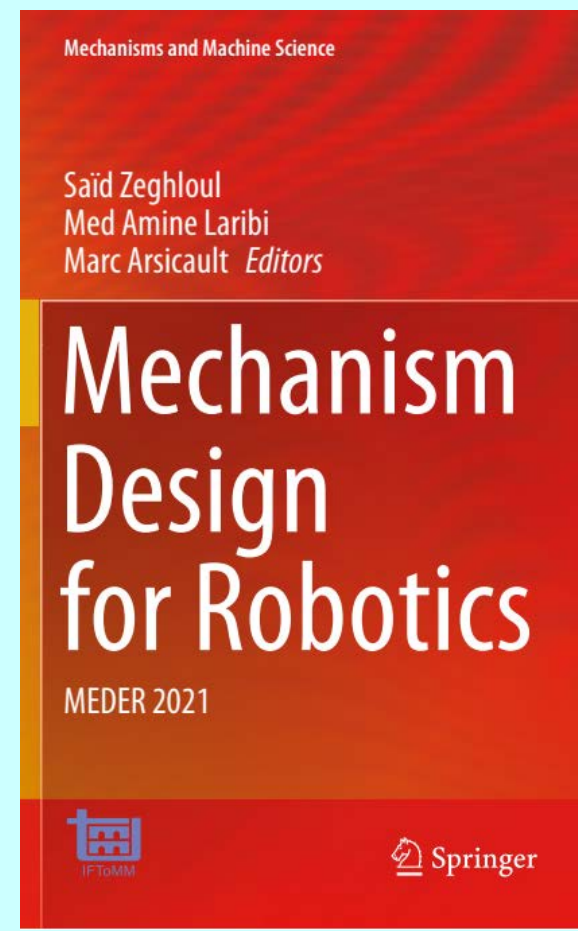
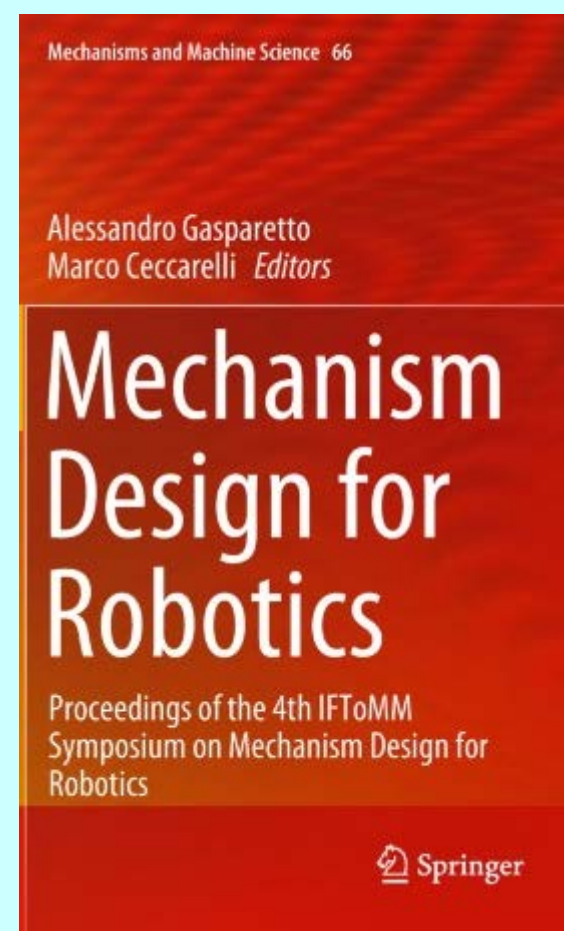
5th IFTOMM Symposium on
Mechanism Design for Robotics
MEDER 2021
June 23-25, 2021
Futuroscope-Poitiers, France

Call For Papers - Teleconference



Proceedings

2015: Aalborg



2018: Udine

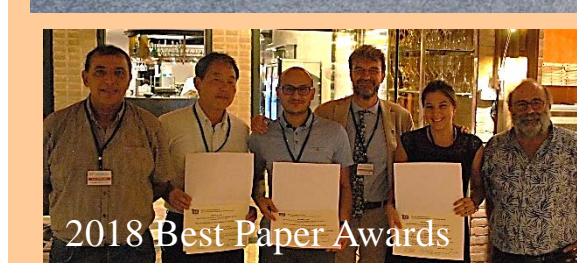
2021: Poitiers

2010: Mexico city



2012: Beijing

International participation and social program.



ISC Meetings

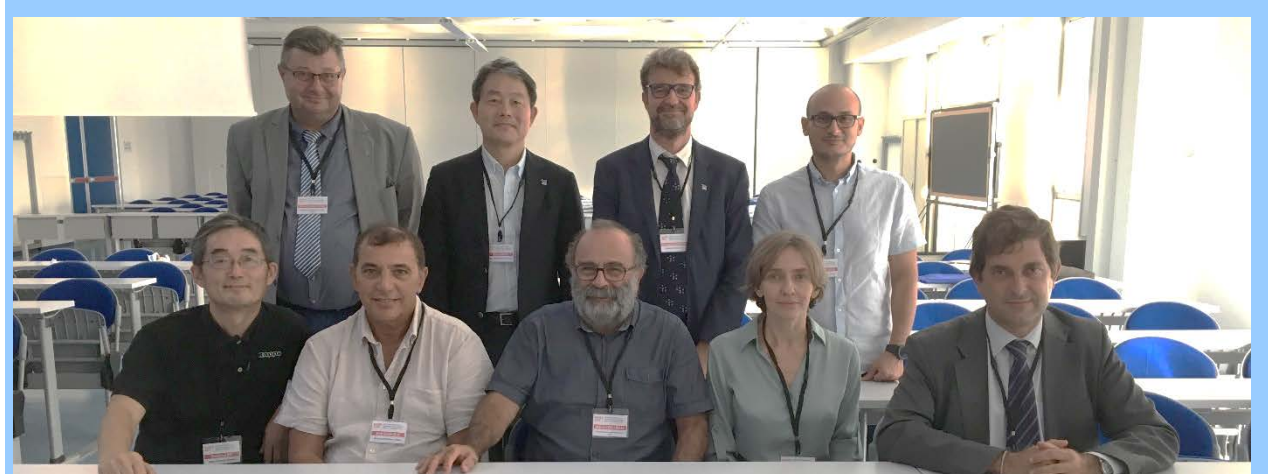
2010 Mexico city



Starting promoters:
M. Ceccarelli
M. Acevedo
J. Rooney
T. Koetsier
I. Jokowski
J.A. Carretero
G. Gogu



2015 Aalborg: Mario Acevedo, Alba Perez, Marco Ceccarelli, Alfonso Hernandez, Yukio Takeda, Yan Jin, Victor Petuya, Shaoping Bai



2018 Udine: Shaoping Bai Said Zeghloul, Marco Ceccarelli, Alba Perez, Victor Petuya, Erwin Lovasz, Yukio Takeda, Alessandro Gasparetto, Amine Laribi